

FREE BOUNDARY CONSTANT MEAN CURVATURE HYPERSURFACES

Maria Andrade
Universidade Federal de Sergipe - Brazil
Lecture 2

CIMPA/ICTP RESEARCH IN PAIRS

Supported also by CNPq Grant 403349/2021-4

June 13, 2023

- This is a mini-course at master/beginning of PhD level.
 - ① Some classic results.
 - ② Free boundary CMC (minimal) (hyper)surfaces in the ball.
 - ③ Gaps results.
 - ④ Stability.
 - ⑤ Index.
 - ⑥ The Steklov Eigenvalue Problem.
 - ⑦ Some characterization of the critical catenoid.
 - ⑧ Some open problems.

① Lecture 1

- (Brief) Motivation to study Differential Geometry. (done)

① Lecture 1

- (Brief) Motivation to study Differential Geometry. (done)

② Lecture 2

- Free boundary minimal or CMC (hyper)surfaces. Gap results.

① Lecture 1

- (Brief) Motivation to study Differential Geometry. (done)

② Lecture 2

- Free boundary minimal or CMC (hyper)surfaces. Gap results.

③ Lecture 3

- Free boundary CMC (hyper)surface in the ball. Stability.

④ Lecture 4

- Some characterization of the critical catenoid. Index.

Lecture 2

① Introduction/Motivation

② Results

③ References

- In 1853, **Jellet** showed that any closed star-shaped CMC surface in \mathbb{R}^3 is a round sphere.

¹Wang, G. Rigidity of Free Boundary CMC Hypersurfaces in a Ball.

- In 1853, **Jellet** showed that any closed star-shaped CMC surface in \mathbb{R}^3 is a round sphere.
- **Hopf**, in 1956, proved that any closed immersed CMC topological 2-sphere in \mathbb{R}^3 is a round sphere.

¹Wang, G. Rigidity of Free Boundary CMC Hypersurfaces in a Ball.

- In 1853, **Jellet** showed that any closed star-shaped CMC surface in \mathbb{R}^3 is a round sphere.
- **Hopf**, in 1956, proved that any closed immersed CMC topological 2-sphere in \mathbb{R}^3 is a round sphere.
- Hopf conjectured that the condition of **topological 2-sphere** can be removed.

¹Wang, G. Rigidity of Free Boundary CMC Hypersurfaces in a Ball.

- In 1853, **Jellet** showed that any closed star-shaped CMC surface in \mathbb{R}^3 is a round sphere.
- **Hopf**, in 1956, proved that any closed immersed CMC topological 2-sphere in \mathbb{R}^3 is a round sphere.
- Hopf conjectured that the condition of **topological 2-sphere** can be removed.
- In 1958, **Alexandrov** gave an affirmative answer to Hopf's conjecture in the case that the surface is assumed to be embedded. He invented nowadays so-called "Alexandrov reflection method" or "moving plane method".

¹Wang, G. Rigidity of Free Boundary CMC Hypersurfaces in a Ball.

- In 1853, **Jellet** showed that any closed star-shaped CMC surface in \mathbb{R}^3 is a round sphere.
- **Hopf**, in 1956, proved that any closed immersed CMC topological 2-sphere in \mathbb{R}^3 is a round sphere.
- Hopf conjectured that the condition of **topological 2-sphere** can be removed.
- In 1958, **Alexandrov** gave an affirmative answer to Hopf's conjecture in the case that the surface is assumed to be embedded. He invented nowadays so-called "Alexandrov reflection method" or "moving plane method".
- In 1982, **Barbosa - do Carmo**, proved that any closed immersed stable CMC hypersurface is a round sphere. (Here stability means the second variation of the area functional is nonnegative for any volume-preserving variation.)

¹Wang, G. Rigidity of Free Boundary CMC Hypersurfaces in a Ball.

- In 1853, **Jellet** showed that any closed star-shaped CMC surface in \mathbb{R}^3 is a round sphere.
- **Hopf**, in 1956, proved that any closed immersed CMC topological 2-sphere in \mathbb{R}^3 is a round sphere.
- Hopf conjectured that the condition of **topological 2-sphere** can be removed.
- In 1958, **Alexandrov** gave an affirmative answer to Hopf's conjecture in the case that the surface is assumed to be embedded. He invented nowadays so-called "Alexandrov reflection method" or "moving plane method".
- In 1982, **Barbosa - do Carmo**, proved that any closed immersed stable CMC hypersurface is a round sphere. (Here stability means the second variation of the area functional is nonnegative for any volume-preserving variation.)
- In 1982, **Hsiang et al.** constructed a CMC topological 3-sphere in \mathbb{R}^4 , which is not round sphere.

¹Wang, G. Rigidity of Free Boundary CMC Hypersurfaces in a Ball.

- In 1853, **Jellet** showed that any closed star-shaped CMC surface in \mathbb{R}^3 is a round sphere.
- **Hopf**, in 1956, proved that any closed immersed CMC topological 2-sphere in \mathbb{R}^3 is a round sphere.
- Hopf conjectured that the condition of **topological 2-sphere** can be removed.
- In 1958, **Alexandrov** gave an affirmative answer to Hopf's conjecture in the case that the surface is assumed to be embedded. He invented nowadays so-called "Alexandrov reflection method" or "moving plane method".
- In 1982, **Barbosa - do Carmo**, proved that any closed immersed stable CMC hypersurface is a round sphere. (Here stability means the second variation of the area functional is nonnegative for any volume-preserving variation.)
- In 1982, **Hsiang et al.** constructed a CMC topological 3-sphere in \mathbb{R}^4 , which is not round sphere.
- In 1986, **Wente** constructed a CMC immersion of 2-torus in \mathbb{R}^3 , which disproves Hopf's conjecture. ¹

¹Wang, G. Rigidity of Free Boundary CMC Hypersurfaces in a Ball.

Definition

Let $x : \Sigma^2 \rightarrow \mathbb{B}^3$ be an isometric immersion, where Σ is a smooth compact surface with $\Sigma \cap \partial\mathbb{B}^3 = \partial\Sigma$.

Definition

Let $x : \Sigma^2 \rightarrow \mathbb{B}^3$ be an isometric immersion, where Σ is a smooth compact surface with $\Sigma \cap \partial\mathbb{B}^3 = \partial\Sigma$. We say that Σ is a *free boundary CMC surface* if

- Σ^2 has mean curvature vector \vec{H} length constant.
- Σ^2 intersects $\partial\mathbb{B}^3 = \mathbb{S}^2$ in a right angle along its boundary $\partial\Sigma$.

Definition

Let $x : \Sigma^2 \rightarrow \mathbb{B}^3$ be an isometric immersion, where Σ is a smooth compact surface with $\Sigma \cap \partial\mathbb{B}^3 = \partial\Sigma$. We say that Σ is a **free boundary CMC surface** if

- Σ^2 has mean curvature vector \vec{H} length constant.
- Σ^2 intersects $\partial\mathbb{B}^3 = \mathbb{S}^2$ in a right angle along its boundary $\partial\Sigma$.

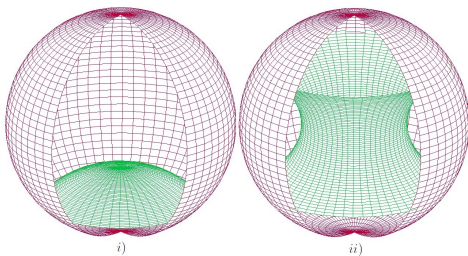


Figure: Image by Barbosa, Cavalcante and Pereira.

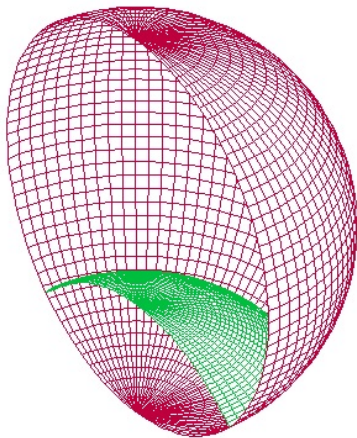


Figure: Spherical cap. Image by Barbosa, Cavalcante and Pereira.

Trivial: equatorial disc

$$\mathbb{D}^2 = \{(x_1, x_2, 0) \in \mathbb{B}_1^3; x_1^2 + x_2^2 \leq 1\}$$

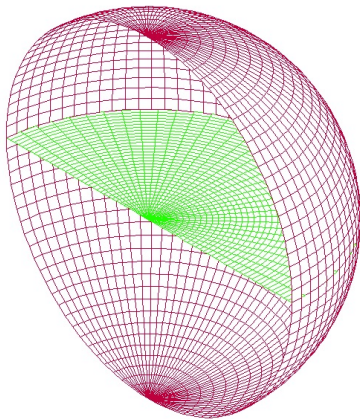


Figure: Image by Barbosa, Cavalcante and Pereira.

Critical catenoid

$\Sigma^2 = \{(a \cosh(\frac{t}{a}) \cos(\theta), a \cosh(\frac{t}{a}) \sin(\theta), t) \in \mathbb{B}_1^3\}$ where
 $\theta \in [0, 2\pi], -ak_0 \leq t \leq ak_0$ and $k_0 > 0$ is the solution of $\cosh(k_0) = \frac{1}{k_0}$ e
 $a = \frac{1}{\sqrt{\cosh^2(k_0) + k_0^2}}$

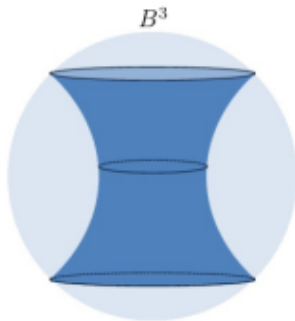


Figure: Image by Tayanara Santos.

Consider Σ^k a compact k -dimensional immersed submanifold an n -dimensional Riemannian manifold M with boundary $\partial\Sigma \subset \partial M$.

Consider Σ^k a compact k -dimensional immersed submanifold an n -dimensional Riemannian manifold M with boundary $\partial\Sigma \subset \partial M$. Let

$$\Phi_t : \Sigma \rightarrow M$$

be an one-parameter family of immersions with $\Phi_t(\partial\Sigma) \subset \partial M$, $t \in (-\epsilon, \epsilon)$, with F_0 given by the inclusion $\Sigma \hookrightarrow M$.

Consider Σ^k a compact k -dimensional immersed submanifold an n -dimensional Riemannian manifold M with boundary $\partial\Sigma \subset \partial M$. Let

$$\Phi_t : \Sigma \rightarrow M$$

be an one-parameter family of immersions with $\Phi_t(\partial\Sigma) \subset \partial M$, $t \in (-\epsilon, \epsilon)$, with F_0 given by the inclusion $\Sigma \hookrightarrow M$. The first variation of volume is:

$$\frac{d}{dt}\bigg|_{t=0} |\Phi_t(M)| = - \int_{\Sigma} \langle X, H \rangle d\mu_{\Sigma} + \int_{\partial\Sigma} \langle X, \eta \rangle d\mu_{\partial\Sigma},$$

where

- η is the outward with unit conormal vector of $\partial\Sigma$.
- H is the mean curvature vector of Σ in M .
- $X = \frac{d\Phi}{dt}\big|_{t=0}$ is the variation field.
- $\frac{d}{dt}\big|_{t=0} |\Phi_t(M)| = 0 \iff H = 0$ and $\Sigma \perp \partial M$ along $\partial\Sigma$.

Consider Σ^k a compact k -dimensional immersed submanifold in an n -dimensional Riemannian manifold M with boundary $\partial\Sigma \subset \partial M$. Let

$$\Phi_t : \Sigma \rightarrow M$$

be a one-parameter family of immersions with $\Phi_t(\partial\Sigma) \subset \partial M$, $t \in (-\epsilon, \epsilon)$, with F_0 given by the inclusion $\Sigma \hookrightarrow M$. The first variation of volume is:

$$\frac{d}{dt}\bigg|_{t=0} |\Phi_t(M)| = - \int_{\Sigma} \langle X, H \rangle d\mu_{\Sigma} + \int_{\partial\Sigma} \langle X, \eta \rangle d\mu_{\partial\Sigma},$$

where

- η is the outward unit conormal vector of $\partial\Sigma$.
- H is the mean curvature vector of Σ in M .
- $X = \frac{d\Phi}{dt}\big|_{t=0}$ is the variation field.
- $\frac{d}{dt}\big|_{t=0} |\Phi_t(M)| = 0 \iff H = 0$ and $\Sigma \perp \partial M$ along $\partial\Sigma$.
- The first variation formula shows that free boundary CMC surfaces are critical points of the area functional for volume preserving variations of Σ , whose $\partial\Sigma$ is free to move in ∂M .

Ros and Vergasta studied compact, stable, CMC hypersurfaces with free boundary in the ball $\mathbb{B} \subset \mathbb{R}^{n+1}$:

Theorem (Ros - Vergasta - 1995)

Let $\mathbb{B}^3 \subset \mathbb{R}^3$ be a closed ball. If $\Sigma^2 \subset \mathbb{B}^3$ is an immersed orientable compact *stable* CMC surface with free boundary, then $\partial\Sigma$ is embedded and the only possibilities are

- ① Σ is a totally geodesic disk.
- ② Σ is a spherical cap;
- ③ Σ has genus 1 with at most two boundary components.

Theorem (Nunes - 2017)

*Let $\mathbb{B}^3 \subset \mathbb{R}^3$ be a closed ball. If $\Sigma^2 \subset \mathbb{B}^3$ is an immersed orientable compact **stable** CMC surface with free boundary, then Σ^2 has genus zero.*

Theorem (Nunes - 2017)

*Let $\mathbb{B}^3 \subset \mathbb{R}^3$ be a closed ball. If $\Sigma^2 \subset \mathbb{B}^3$ is an immersed orientable compact **stable** CMC surface with free boundary, then Σ^2 has genus zero.*

Remark:

As a consequence of Ros-Vergasta and Nunes, was complete classification of immersed compact stable CMC surfaces with free boundary in closed balls of \mathbb{R}^3 .

Corollary (Nunes - 2017)

The totally umbilical disks are the only immersed orientable compact stable CMC surfaces with free boundary in a closed ball $\mathbb{B}^3 \subset \mathbb{R}^3$.

Existence and Classification

- Struwe - 1988, Jost and Grüter - 1986: showed the existence of properly embedded free boundary minimal disks inside strictly convex subsets of \mathbb{R}^3 .

- Struwe - 1988, Jost and Grüter - 1986: showed the existence of properly embedded free boundary minimal disks inside strictly convex subsets of \mathbb{R}^3 .
- Máximo, Nunes and Smith - 2017: existence of free boundary minimal annuli inside suitably convex subsets of three-dimensional Riemannian manifolds of nonnegative Ricci curvature. This includes strictly convex domains in \mathbb{R}^3 .

- Struwe - 1988, Jost and Grüter - 1986: showed the existence of properly embedded free boundary minimal disks inside strictly convex subsets of \mathbb{R}^3 .
- Máximo, Nunes and Smith - 2017: existence of free boundary minimal annuli inside suitably convex subsets of three-dimensional Riemannian manifolds of nonnegative Ricci curvature. This includes strictly convex domains in \mathbb{R}^3 .
- Fraser and Schoen - 2016: Proved the existence of minimal free boundary surfaces on the Euclidean unit ball \mathbb{B}^3 with zero genus and r boundary components for any $r \geq 3$ fixed.

- Struwe - 1988, Jost and Grüter - 1986: showed the existence of properly embedded free boundary minimal disks inside strictly convex subsets of \mathbb{R}^3 .
- Máximo, Nunes and Smith - 2017: existence of free boundary minimal annuli inside suitably convex subsets of three-dimensional Riemannian manifolds of nonnegative Ricci curvature. This includes strictly convex domains in \mathbb{R}^3 .
- Fraser and Schoen - 2016: Proved the existence of minimal free boundary surfaces on the Euclidean unit ball \mathbb{B}^3 with zero genus and r boundary components for any $r \geq 3$ fixed.
- Folha, Pacard and Zolotareva - 2016: From a sufficiently large r there is a surface of genus 1 and r components on the boundary.

- Struwe - 1988, Jost and Grüter - 1986: showed the existence of properly embedded free boundary minimal disks inside strictly convex subsets of \mathbb{R}^3 .
- Máximo, Nunes and Smith - 2017: existence of free boundary minimal annuli inside suitably convex subsets of three-dimensional Riemannian manifolds of nonnegative Ricci curvature. This includes strictly convex domains in \mathbb{R}^3 .
- Fraser and Schoen - 2016: Proved the existence of minimal free boundary surfaces on the Euclidean unit ball \mathbb{B}^3 with zero genus and r boundary components for any $r \geq 3$ fixed.
- Folha, Pacard and Zolotareva - 2016: From a sufficiently large r there is a surface of genus 1 and r components on the boundary.
- Ketover - 2017: For any value of genus $g \geq 1$ there exists a minimal free boundary surface on \mathbb{B}^3 with genus g .

Geometric Analysis Gallery - Mario B. Schulz's homepage

- Nitsche - 1985 Let Σ^2 be a compact free boundary minimal surface in $\mathbb{B}^3 \subset \mathbb{R}^3$. If Σ^2 is topologically equivalent a disk, then Σ^2 is a plane equatorial disk.

- Nitsche - 1985 Let Σ^2 be a compact free boundary minimal surface in $\mathbb{B}^3 \subset \mathbb{R}^3$. If Σ^2 is topologically equivalent a disk, then Σ^2 is a plane equatorial disk.
- This result was extended to free boundary minimal disks in geodesic ball in the three-dimensional **spaces forms** of constant curvature by Ros - Souam in 1997 and after by Souam - 1997 (hypersurfaces).

- Nitsche - 1985 Let Σ^2 be a compact free boundary minimal surface in $\mathbb{B}^3 \subset \mathbb{R}^3$. If Σ^2 is topologically equivalent a disk, then Σ^2 is a plane equatorial disk.
- This result was extended to free boundary minimal disks in geodesic ball in the three-dimensional **spaces forms** of constant curvature by Ros - Souam in 1997 and after by Souam - 1997 (hypersurfaces).
- Fraser and Schoen - 2015: generalized Nitsche's result to free boundary minimal disk in geodesic ball of arbitrary dimension in **spaces forms**, i.e., flat equatorial disk $\Sigma^2 \subset B^{n+1}$ is the only free boundary minimal disk in the balls of a **space form**.

GAP RESULTS

Theorem (Chern - do Carmo - Kobayashi - 1970; Lawson 1969)

Let Σ^n be a closed minimal hypersurface in the unit sphere \mathbb{S}^{n+1} .

Theorem (Chern - do Carmo - Kobayashi - 1970; Lawson 1969)

Let Σ^n be a closed minimal hypersurface in the unit sphere \mathbb{S}^{n+1} . Suppose that the second fundamental form A satisfies

$$|A|^2 \leq n.$$

Then,

- *either $|A|^2 = 0$ and Σ is an equator.*
- *or $|A|^2 = n$ and Σ is a Clifford hypersurface (product of two round spheres of appropriate radius and dimensions).*

Theorem (Ambrozio - Nunes - 2016)

Let Σ^2 be a compact free boundary minimal surface in \mathbb{B}^3 . Assume that

$$|A|^2(x) \langle x, N(x) \rangle^2 \leq 2, \forall x \in \Sigma,$$

Theorem (Ambrozio - Nunes - 2016)

Let Σ^2 be a compact free boundary minimal surface in \mathbb{B}^3 . Assume that

$$|A|^2(x)\langle x, N(x)\rangle^2 \leq 2, \forall x \in \Sigma,$$

where $N(x)$ denotes a unit normal vector at the point $x \in \Sigma$ and A denotes the second fundamental form of Σ . Then

- 1 either $|A|^2(x)\langle x, N(x)\rangle^2 = 0$ and Σ is a flat equatorial disk;
- 2 $|A|^2(p)\langle p, N(p)\rangle^2 = 2$ at some point $p \in \Sigma$ and Σ is a critical catenoid.

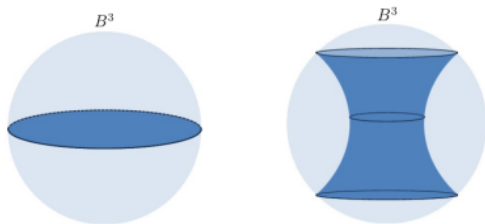


Figure: Image by Tayanara Santos.

- Define $f(x) = \frac{|x|^2}{2}$ $x \in \Sigma$.

- Define $f(x) = \frac{|x|^2}{2}$ $x \in \Sigma$.
- $\nabla^\Sigma f(x) = x$ on $\partial\Sigma$.

- Define $f(x) = \frac{|x|^2}{2}$ $x \in \Sigma$.
- $\nabla^\Sigma f(x) = x$ on $\partial\Sigma$.
- The geodesic curvature of $\partial\Sigma$ in Σ is equal to 1.

- Define $f(x) = \frac{|x|^2}{2}$ $x \in \Sigma$.
- $\nabla^\Sigma f(x) = x$ on $\partial\Sigma$.
- The geodesic curvature of $\partial\Sigma$ in Σ is equal to 1. Then $\partial\Sigma$ is strictly convex in Σ . This shows that, for all points $p, q \in \Sigma$ there is a minimising geodesic in Σ joining p to q .

- Define $f(x) = \frac{|x|^2}{2}$ $x \in \Sigma$.
- $\nabla^\Sigma f(x) = x$ on $\partial\Sigma$.
- The geodesic curvature of $\partial\Sigma$ in Σ is equal to 1. Then $\partial\Sigma$ is strictly convex in Σ . This shows that, for all points $p, q \in \Sigma$ there is a minimising geodesic in Σ joining p to q .
- Eigenvalues of $\text{Hess} f(x)$ are given by $1 \pm \frac{|A|(x)}{\sqrt{2}} \langle x, N \rangle$.

- Define $f(x) = \frac{|x|^2}{2}$ $x \in \Sigma$.
- $\nabla^\Sigma f(x) = x$ on $\partial\Sigma$.
- The geodesic curvature of $\partial\Sigma$ in Σ is equal to 1. Then $\partial\Sigma$ is strictly convex in Σ . This shows that, for all points $p, q \in \Sigma$ there is a minimising geodesic in Σ joining p to q .
- Eigenvalues of $\text{Hess}f(x)$ are given by $1 \pm \frac{|A|(x)}{\sqrt{2}} \langle x, N \rangle$.
- $|A|^2(x) \langle x, N(x) \rangle^2 \leq 2 \iff \text{Hess}f(x) \geq 0$.

- Define $f(x) = \frac{|x|^2}{2}$ $x \in \Sigma$.
- $\nabla^\Sigma f(x) = x$ on $\partial\Sigma$.
- The geodesic curvature of $\partial\Sigma$ in Σ is equal to 1. Then $\partial\Sigma$ is strictly convex in Σ . This shows that, for all points $p, q \in \Sigma$ there is a minimising geodesic in Σ joining p to q .
- Eigenvalues of $\text{Hess}f(x)$ are given by $1 \pm \frac{|A|(x)}{\sqrt{2}} \langle x, N \rangle$.
- $|A|^2(x) \langle x, N(x) \rangle^2 \leq 2 \iff \text{Hess}f(x) \geq 0$.
- $C = \{x \in \Sigma; |p| = \min_{x \in \Sigma} |x|\}$.
- $\text{Hess}f(x) \geq 0 \Rightarrow C$ is totally convex i.e., any geodesic arc γ joining two points in C is entirely contained in C .

- Define $f(x) = \frac{|x|^2}{2}$ $x \in \Sigma$.
- $\nabla^\Sigma f(x) = x$ on $\partial\Sigma$.
- The geodesic curvature of $\partial\Sigma$ in Σ is equal to 1. Then $\partial\Sigma$ is strictly convex in Σ . This shows that, for all points $p, q \in \Sigma$ there is a minimising geodesic in Σ joining p to q .
- Eigenvalues of $\text{Hess}f(x)$ are given by $1 \pm \frac{|A|(x)}{\sqrt{2}} \langle x, N \rangle$.
- $|A|^2(x) \langle x, N(x) \rangle^2 \leq 2 \iff \text{Hess}f(x) \geq 0$.
- $C = \{x \in \Sigma; |p| = \min_{x \in \Sigma} |x|\}$.
- $\text{Hess}f(x) \geq 0 \Rightarrow C$ is totally convex i.e., any geodesic arc γ joining two points in C is entirely contained in C .
- If $C = \{p\}$, then Σ is a topologically disk.

$$|A|^2(x) \langle x, N(x) \rangle^2 < 2 \Rightarrow C = \{p\}$$

$$\Rightarrow \Sigma \text{ is a disk}$$

$$\text{Nistsche} \Rightarrow \Sigma \text{ is an equatorial disk.}$$

- Define $f(x) = \frac{|x|^2}{2}$ $x \in \Sigma$.
- $\nabla^\Sigma f(x) = x$ on $\partial\Sigma$.
- The geodesic curvature of $\partial\Sigma$ in Σ is equal to 1. Then $\partial\Sigma$ is strictly convex in Σ . This shows that, for all points $p, q \in \Sigma$ there is a minimising geodesic in Σ joining p to q .
- Eigenvalues of $\text{Hess}f(x)$ are given by $1 \pm \frac{|A|(x)}{\sqrt{2}} \langle x, N \rangle$.
- $|A|^2(x) \langle x, N(x) \rangle^2 \leq 2 \iff \text{Hess}f(x) \geq 0$.
- $C = \{x \in \Sigma; |p| = \min_{x \in \Sigma} |x|\}$.
- $\text{Hess}f(x) \geq 0 \Rightarrow C$ is totally convex i.e., any geodesic arc γ joining two points in C is entirely contained in C .
- If $C = \{p\}$, then Σ is a topologically disk.

$$|A|^2(x) \langle x, N(x) \rangle^2 < 2 \Rightarrow C = \{p\}$$

$$\Rightarrow \Sigma \text{ is a disk}$$

$$\text{Nistsche} \Rightarrow \Sigma \text{ is an equatorial disk.}$$

- If $C \neq \{p\}$, then Σ is an homeomorphic to an annulus and C is a closed geodesic.

- Define $f(x) = \frac{|x|^2}{2}$ $x \in \Sigma$.
- $\nabla^\Sigma f(x) = x$ on $\partial\Sigma$.
- The geodesic curvature of $\partial\Sigma$ in Σ is equal to 1. Then $\partial\Sigma$ is strictly convex in Σ . This shows that, for all points $p, q \in \Sigma$ there is a minimising geodesic in Σ joining p to q .
- Eigenvalues of $\text{Hess}f(x)$ are given by $1 \pm \frac{|A|(x)}{\sqrt{2}} \langle x, N \rangle$.
- $|A|^2(x) \langle x, N(x) \rangle^2 \leq 2 \iff \text{Hess}f(x) \geq 0$.
- $C = \{x \in \Sigma; |p| = \min_{x \in \Sigma} |x|\}$.
- $\text{Hess}f(x) \geq 0 \Rightarrow C$ is totally convex i.e., any geodesic arc γ joining two points in C is entirely contained in C .
- If $C = \{p\}$, then Σ is a topologically disk.

$$|A|^2(x) \langle x, N(x) \rangle^2 < 2 \Rightarrow C = \{p\}$$

$$\Rightarrow \Sigma \text{ is a disk}$$

$$\text{Nistsche} \Rightarrow \Sigma \text{ is an equatorial disk.}$$

- If $C \neq \{p\}$, then Σ is homeomorphic to an annulus and C is a closed geodesic.
- We can prove that C is a great circle and $N(p) = p \forall p \in C$.

- Define $f(x) = \frac{|x|^2}{2}$ $x \in \Sigma$.
- $\nabla^\Sigma f(x) = x$ on $\partial\Sigma$.
- The geodesic curvature of $\partial\Sigma$ in Σ is equal to 1. Then $\partial\Sigma$ is strictly convex in Σ . This shows that, for all points $p, q \in \Sigma$ there is a minimising geodesic in Σ joining p to q .
- Eigenvalues of $\text{Hess}f(x)$ are given by $1 \pm \frac{|A|(x)}{\sqrt{2}} \langle x, N \rangle$.
- $|A|^2(x) \langle x, N(x) \rangle^2 \leq 2 \iff \text{Hess}f(x) \geq 0$.
- $C = \{x \in \Sigma; |p| = \min_{x \in \Sigma} |x|\}$.
- $\text{Hess}f(x) \geq 0 \Rightarrow C$ is totally convex i.e., any geodesic arc γ joining two points in C is entirely contained in C .
- If $C = \{p\}$, then Σ is a topologically disk.

$$|A|^2(x) \langle x, N(x) \rangle^2 < 2 \Rightarrow C = \{p\}$$

$$\Rightarrow \Sigma \text{ is a disk}$$

$$\text{Nistsche} \Rightarrow \Sigma \text{ is an equatorial disk.}$$

- If $C \neq \{p\}$, then Σ is homeomorphic to an annulus and C is a closed geodesic.
- We can prove that C is a great circle and $N(p) = p \forall p \in C$.
- Σ is a critical catenoid by the solution to Björling problem.

Consider $X : [-t_0, t_0] \times [0, 2\pi] \rightarrow \mathbb{R}^3$ parametrization of a piece of catenoid contained in \mathbb{B}^3 , meeting $\partial\mathbb{B}^3$ orthogonally

$$X(t, \theta) = (a_0 \cosh(t) \cos(\theta), a_0 \cosh(t) \sin(\theta), a_0 t),$$

the constant t_0 is the unique positive solution to the equation $t \sinh(t) = \cosh(t)$, while $a_0 = (t_0 \cosh(t_0))^{-1}$.

Consider $X : [-t_0, t_0] \times [0, 2\pi] \rightarrow \mathbb{R}^3$ parametrization of a piece of catenoid contained in \mathbb{B}^3 , meeting $\partial\mathbb{B}^3$ orthogonally

$$X(t, \theta) = (a_0 \cosh(t) \cos(\theta), a_0 \cosh(t) \sin(\theta), a_0 t),$$

the constant t_0 is the unique positive solution to the equation $t \sinh(t) = \cosh(t)$, while $a_0 = (t_0 \cosh(t_0))^{-1}$. We can prove that

$$|A|^2 = \frac{2}{a_0^2 \cosh^4(t)} \text{ and } \langle x, N \rangle^2 = a_0^2 \left(1 - \frac{t \sinh(t)}{\cosh(t)} \right)^2.$$

Consider $X : [-t_0, t_0] \times [0, 2\pi] \rightarrow \mathbb{R}^3$ parametrization of a piece of catenoid contained in \mathbb{B}^3 , meeting $\partial\mathbb{B}^3$ orthogonally

$$X(t, \theta) = (a_0 \cosh(t) \cos(\theta), a_0 \cosh(t) \sin(\theta), a_0 t),$$

the constant t_0 is the unique positive solution to the equation $t \sinh(t) = \cosh(t)$, while $a_0 = (t_0 \cosh(t_0))^{-1}$. We can prove that

$$|A|^2 = \frac{2}{a_0^2 \cosh^4(t)} \text{ and } \langle x, N \rangle^2 = a_0^2 \left(1 - \frac{t \sinh(t)}{\cosh(t)} \right)^2.$$

Thus,

$$|A|^2 \langle x, N \rangle^2 = \frac{2}{\cosh^6(t)} (\cosh(t) - t \sinh(t))^2 \leq 2.$$

Conjecture (Fraser - Li - 2012)

The critical catenoid is the only embedded free boundary minimal annulus in B^3 , up to rigid motions.

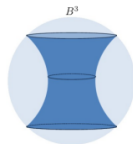


Figure: Image by Tayanara Santos.

Conjecture (Fraser - Li - 2012)

The critical catenoid is the only embedded free boundary minimal annulus in B^3 , up to rigid motions.

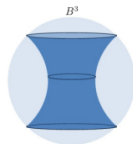


Figure: Image by Tayanara Santos.

Conjecture (Lawson-1970)

The Clifford torus is the only embedded minimal torus in \mathbb{S}^3 , up to rigid motions.

It was proved by S. Brendle. S. Brendle, Embedded minimal tori in \mathbb{S}^3 and the Lawson conjecture, *Acta Math.* 211(2), 177-190 (2013).

Theorem (Barbosa - Cavalcante - Pereira - 2019)

Let Σ^2 be a compact free boundary CMC surface in B^3 . Assume that for all points $x \in \Sigma$,

$$|\overset{\circ}{A}|^2 \langle x, N \rangle^2 \leq \frac{1}{2} (2 + H \langle x, N \rangle)^2, \quad (1)$$

where $\overset{\circ}{A} = II - \frac{H}{2} g_\Sigma$. Then

- 1 either $|\overset{\circ}{A}|^2 \langle x, N \rangle^2 = 0$ and Σ is spherical cap.
- 2 or equality in (1) occurs at some point and Σ is a part of Delaunay surface.

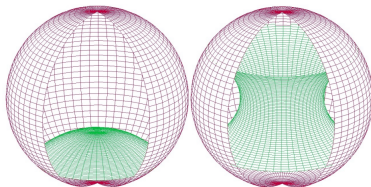


Figure: Image by Barbosa, Cavalcante and Pereira.

The proof is inspired in the work of Ambrozio and Nunes and the conclusion follows by analyzing of the convexity of the function $\varphi(x) = \frac{|x|^2}{2}$ restrict to the surface Σ .

The proof is inspired in the work of Ambrozio and Nunes and the conclusion follows by analyzing of the convexity of the function $\varphi(x) = \frac{|x|^2}{2}$ restrict to the surface Σ .

Steps:

- The first one was to obtain the correct condition which generalizes the gap in Ambrozio-Nunes - 2019 .

The proof is inspired in the work of Ambrozio and Nunes and the conclusion follows by analyzing of the convexity of the function $\varphi(x) = \frac{|x|^2}{2}$ restrict to the surface Σ .

Steps:

- The first one was to obtain the correct condition which generalizes the gap in Ambrozio-Nunes - 2019 .
- Guarantee that condition

$$|\mathring{A}|^2 \langle x, N \rangle^2 \leq \frac{1}{2} (2 + H \langle x, N \rangle)^2,$$

implies that $Hess_{\Sigma} \varphi \geq 0$. The complex structure of the CMC surfaces was essential.

The proof is inspired in the work of Ambrozio and Nunes and the conclusion follows by analyzing of the convexity of the function $\varphi(x) = \frac{|x|^2}{2}$ restrict to the surface Σ .

Steps:

- The first one was to obtain the correct condition which generalizes the gap in Ambrozio-Nunes - 2019 .
- Guarantee that condition

$$|\overset{\circ}{A}|^2 \langle x, N \rangle^2 \leq \frac{1}{2} (2 + H \langle x, N \rangle)^2,$$

implies that $Hess_{\Sigma} \varphi \geq 0$. The complex structure of the CMC surfaces was essential.

- Check that there are some rotational CMC annulus in the unit Euclidean ball \mathbb{B}^3 .

Andrade - Barbosa - Pereira results

- $\mathbb{B}_a^3 \subset \mathbb{R}^3$, $a < \infty$ or $a = \infty$,
- $u : [0, a^2) \rightarrow \mathbb{R}$ smooth,
- $h : \mathbb{B}_a^3 \rightarrow \mathbb{R}$ given by $h(x) = u(|x|^2)$,

Model Manifold

- $(\mathbb{B}_r^3, \bar{g})$.

Where

$$r < a$$

$$\bar{g} = e^{2h} \langle , \rangle$$

- If $u : [0, \infty) \rightarrow \mathbb{R}$ is given by $u(t) = 0$, then $\bar{g} = \langle , \rangle$.

$$(\mathbb{R}^3, \bar{g}) \sim \mathbb{R}^3$$

- If $u : [0, \infty) \rightarrow \mathbb{R}$ is given by $u(t) = 0$, then $\bar{g} = \langle , \rangle$.

$$(\mathbb{R}^3, \bar{g}) \sim \mathbb{R}^3$$

- If $u : [0, 1) \rightarrow \mathbb{R}$ is given by $u(t) = \ln \left(\frac{2}{1-t} \right)$, then $\bar{g} = \frac{4}{(1-|x|^2)^2} \langle , \rangle$.

$$(\mathbb{B}_1^3, \bar{g}) \sim \mathbb{H}^3$$

- If $u : [0, \infty) \rightarrow \mathbb{R}$ is given by $u(t) = \ln \left(\frac{2}{1+t} \right)$, then $\bar{g} = \frac{4}{(1+|x|^2)^2} \langle \cdot, \cdot \rangle$.

$$(\mathbb{R}^3, \bar{g}) \sim \mathbb{S}^3 \setminus \{p\}$$

- If $u : [0, \infty) \rightarrow \mathbb{R}$ is given by $u(t) = \ln \left(\frac{2}{1+t} \right)$, then $\bar{g} = \frac{4}{(1+|x|^2)^2} \langle , \rangle$.

$$(\mathbb{R}^3, \bar{g}) \sim \mathbb{S}^3 \setminus \{p\}$$

- If $u : [0, \infty) \rightarrow \mathbb{R}$ is given by $u(t) = -\frac{t}{4}$, then $\bar{g} = e^{-\frac{|x|^2}{4}} \langle , \rangle$.

$$(\mathbb{R}^3, \bar{g}) = \left(\mathbb{R}^3, e^{-\frac{|\vec{x}|^2}{4}} \langle , \rangle \right) \sim \mathbb{G}^3$$

- Let $\bar{\nabla}$ and ∇ be the Riemannian connection of $(\mathbb{B}_r^3, \bar{g})$ e $(\mathbb{B}_r^3, \langle, \rangle)$ respectively.
- \vec{x} position field in \mathbb{B}_r^3

$$(\mathbb{B}_r^3, \langle, \rangle)$$

$$\nabla_Y \vec{x} = Y, \quad \mathcal{L}_{\vec{x}} \langle, \rangle = 2 \langle, \rangle$$

$$(\mathbb{B}_r^3, \bar{g})$$

$$\bar{\nabla}_Y \vec{x} = \sigma Y, \quad \mathcal{L}_{\vec{x}} \bar{g} = 2\sigma \bar{g}$$

where

$$\sigma(x) = 1 + 2u'(|x|^2)|x|^2$$

Theorem (A., Barbosa, Pereira)

Let Σ^2 be a compact free boundary CMC surface in $(\mathbb{B}_r^3, \bar{g})$. Suppose that for all points $x \in \Sigma$,

$$\left\{ \begin{array}{lcl} \frac{|\mathring{A}|^2}{\sigma^2} \bar{g}(\vec{x}, N)^2 & \leq & \frac{1}{2} \left(2 + \frac{H}{\sigma} \bar{g}(\vec{x}, N) \right)^2 \\ 0 & \leq & 2 + \frac{H}{\sigma} \bar{g}(\vec{x}, N). \end{array} \right.$$

Then, one of the following situations occurs,

- ❶ either Σ is diffeomorphic to a disk,
- ❷ or Σ is rotationally symmetric with nontrivial topology.

- $\Psi(x) = \Phi(\varphi(x))$, where $\varphi(x) = \bar{g}(\vec{x}, \vec{x})$

- $\Psi(x) = \Phi(\varphi(x))$, where $\varphi(x) = \bar{g}(\vec{x}, \vec{x})$
- Eigenvalues of $\text{Hess}_{\Sigma} \Psi$:

- $\Psi(x) = \Phi(\varphi(x))$, where $\varphi(x) = \bar{g}(\vec{x}, \vec{x})$
- Eigenvalues of $\text{Hess}_{\Sigma} \Psi$:

$$\bar{\lambda}_i = 2\sigma^2 \Phi'(\varphi) \left(1 + \frac{\bar{k}_i}{\sigma} \bar{g}(\vec{x}, N) \right) \quad \text{for } i = 1 \text{ and } i = 2.$$

- $\Psi(x) = \Phi(\varphi(x))$, where $\varphi(x) = \bar{g}(\vec{x}, \vec{x})$
- Eigenvalues of $\text{Hess}_{\Sigma} \Psi$:

$$\bar{\lambda}_i = 2\sigma^2 \Phi'(\varphi) \left(1 + \frac{\bar{k}_i}{\sigma} \bar{g}(\vec{x}, N) \right) \quad \text{for } i = 1 \text{ and } i = 2.$$

$$\left\{ \begin{array}{lcl} \frac{|\overset{\circ}{A}|^2}{\sigma^2} \bar{g}(\vec{x}, N)^2 & \leq & \frac{1}{2} \left(2 + \frac{H}{\sigma} \bar{g}(\vec{x}, N) \right)^2 \\ 0 & \leq & 2 + \frac{H}{\sigma} \bar{g}(\vec{x}, N). \end{array} \right. \quad (2)$$

- $\Psi(x) = \Phi(\varphi(x))$, where $\varphi(x) = \bar{g}(\vec{x}, \vec{x})$
- Eigenvalues of $\text{Hess}_{\Sigma} \Psi$:

$$\bar{\lambda}_i = 2\sigma^2 \Phi'(\varphi) \left(1 + \frac{\bar{k}_i}{\sigma} \bar{g}(\vec{x}, N) \right) \quad \text{for } i = 1 \text{ and } i = 2.$$

$$\left\{ \begin{array}{l} \frac{|\overset{\circ}{A}|^2}{\sigma^2} \bar{g}(\vec{x}, N)^2 \leq \frac{1}{2} \left(2 + \frac{H}{\sigma} \bar{g}(\vec{x}, N) \right)^2 \\ 0 \leq 2 + \frac{H}{\sigma} \bar{g}(\vec{x}, N). \end{array} \right. \quad (2)$$

- The first inequality ensures that $\bar{\lambda}_1 \cdot \bar{\lambda}_2 \geq 0$ and second ones ensures that $\bar{\lambda}_1 + \bar{\lambda}_2 \geq 0$.

- $\Psi(x) = \Phi(\varphi(x))$, where $\varphi(x) = \bar{g}(\vec{x}, \vec{x})$
- Eigenvalues of $\text{Hess}_\Sigma \Psi$:

$$\bar{\lambda}_i = 2\sigma^2 \Phi'(\varphi) \left(1 + \frac{\bar{k}_i}{\sigma} \bar{g}(\vec{x}, N) \right) \quad \text{for } i = 1 \text{ and } i = 2.$$

$$\begin{cases} \frac{|\overset{\circ}{A}|^2}{\sigma^2} \bar{g}(\vec{x}, N)^2 & \leq \frac{1}{2} \left(2 + \frac{H}{\sigma} \bar{g}(\vec{x}, N) \right)^2 \\ 0 & \leq 2 + \frac{H}{\sigma} \bar{g}(\vec{x}, N). \end{cases} \quad (2)$$

- The first inequality ensures that $\bar{\lambda}_1 \cdot \bar{\lambda}_2 \geq 0$ and second ones ensures that $\bar{\lambda}_1 + \bar{\lambda}_2 \geq 0$.
- Thus, conditions in (2) implies that $\text{Hess}_\Sigma \Psi(x) \geq 0$.
- The geodesic curvature of $\partial\Sigma$ is $\bar{k}_{ge} = \frac{\sigma}{e^{u(r^2)}}$. In particular, since $\sigma > 0$ in \mathbb{B}_r^3 , $\partial\Sigma$, is strictly convex.

- $\Psi(x) = \Phi(\varphi(x))$, where $\varphi(x) = \bar{g}(\vec{x}, \vec{x})$
- Eigenvalues of $\text{Hess}_\Sigma \Psi$:

$$\bar{\lambda}_i = 2\sigma^2 \Phi'(\varphi) \left(1 + \frac{\bar{k}_i}{\sigma} \bar{g}(\vec{x}, N) \right) \quad \text{for } i = 1 \text{ and } i = 2.$$

$$\begin{cases} \frac{|\mathring{A}|^2}{\sigma^2} \bar{g}(\vec{x}, N)^2 & \leq \frac{1}{2} \left(2 + \frac{H}{\sigma} \bar{g}(\vec{x}, N) \right)^2 \\ 0 & \leq 2 + \frac{H}{\sigma} \bar{g}(\vec{x}, N). \end{cases} \quad (2)$$

- The first inequality ensures that $\bar{\lambda}_1 \cdot \bar{\lambda}_2 \geq 0$ and second ones ensures that $\bar{\lambda}_1 + \bar{\lambda}_2 \geq 0$.
- Thus, conditions in (2) implies that $\text{Hess}_\Sigma \Psi(x) \geq 0$.
- The geodesic curvature of $\partial\Sigma$ is $\bar{k}_{ge} = \frac{\sigma}{e^{u(r^2)}}$. In particular, since $\sigma > 0$ in \mathbb{B}_r^3 , $\partial\Sigma$, is strictly convex.
- The set

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_\Sigma \Psi(x)\},$$

is totally convex in Σ .

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- \mathcal{C} contains more than a single point. Let $\gamma : [0, 1] \rightarrow \mathcal{C}$ be a minimizing geodesic joining two points ($\gamma(0), \gamma(1) \in \mathcal{C}$).

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- \mathcal{C} contains more than a single point. Let $\gamma : [0, 1] \rightarrow \mathcal{C}$ be a minimizing geodesic joining two points ($\gamma(0), \gamma(1) \in \mathcal{C}$).
- γ is a geodesic in \mathbb{S}_{λ}^2 , $\lambda < r$.

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- \mathcal{C} contains more than a single point. Let $\gamma : [0, 1] \rightarrow \mathcal{C}$ be a minimizing geodesic joining two points ($\gamma(0), \gamma(1) \in \mathcal{C}$).
- γ is a geodesic in \mathbb{S}_{λ}^2 , $\lambda < r$.
- $\gamma(t)$ is an arc of a great circle.

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- \mathcal{C} contains more than a single point. Let $\gamma : [0, 1] \rightarrow \mathcal{C}$ be a minimizing geodesic joining two points ($\gamma(0), \gamma(1) \in \mathcal{C}$).
- γ is a geodesic in \mathbb{S}_{λ}^2 , $\lambda < r$.
- $\gamma(t)$ is an arc of a great circle.
- Let $\pi \subset \mathbb{R}^3$ be the plane passing through the origin such that $\gamma \subset \pi$, and let E be a unit normal vector in \mathbb{R}^3 orthogonal to π .

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- \mathcal{C} contains more than a single point. Let $\gamma : [0, 1] \rightarrow \mathcal{C}$ be a minimizing geodesic joining two points ($\gamma(0), \gamma(1) \in \mathcal{C}$).
- γ is a geodesic in \mathbb{S}_{λ}^2 , $\lambda < r$.
- $\gamma(t)$ is an arc of a great circle.
- Let $\pi \subset \mathbb{R}^3$ be the plane passing through the origin such that $\gamma \subset \pi$, and let E be a unit normal vector in \mathbb{R}^3 orthogonal to π .
- $V = \vec{x} \wedge E$ (is a Killing vector field in \mathbb{R}^3).

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- \mathcal{C} contains more than a single point. Let $\gamma : [0, 1] \rightarrow \mathcal{C}$ be a minimizing geodesic joining two points ($\gamma(0), \gamma(1) \in \mathcal{C}$).
- γ is a geodesic in \mathbb{S}_{λ}^2 , $\lambda < r$.
- $\gamma(t)$ is an arc of a great circle.
- Let $\pi \subset \mathbb{R}^3$ be the plane passing through the origin such that $\gamma \subset \pi$, and let E be a unit normal vector in \mathbb{R}^3 orthogonal to π .
- $V = \vec{x} \wedge E$ (is a Killing vector field in \mathbb{R}^3).
- $v(x) = \bar{g}(V, N)$.

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- \mathcal{C} contains more than a single point. Let $\gamma : [0, 1] \rightarrow \mathcal{C}$ be a minimizing geodesic joining two points ($\gamma(0), \gamma(1) \in \mathcal{C}$).
- γ is a geodesic in \mathbb{S}_{λ}^2 , $\lambda < r$.
- $\gamma(t)$ is an arc of a great circle.
- Let $\pi \subset \mathbb{R}^3$ be the plane passing through the origin such that $\gamma \subset \pi$, and let E be a unit normal vector in \mathbb{R}^3 orthogonal to π .
- $V = \vec{x} \wedge E$ (is a Killing vector field in \mathbb{R}^3).
- $v(x) = \bar{g}(V, N)$.
- $\Delta_{\Sigma} v + (\bar{Ric}(N) + |A|^2) v = 0$, [v is a Jacob function (Fornari, Ripoll - 2004)].

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- \mathcal{C} contains more than a single point. Let $\gamma : [0, 1] \rightarrow \mathcal{C}$ be a minimizing geodesic joining two points ($\gamma(0), \gamma(1) \in \mathcal{C}$).
- γ is a geodesic in \mathbb{S}_{λ}^2 , $\lambda < r$.
- $\gamma(t)$ is an arc of a great circle.
- Let $\pi \subset \mathbb{R}^3$ be the plane passing through the origin such that $\gamma \subset \pi$, and let E be a unit normal vector in \mathbb{R}^3 orthogonal to π .
- $V = \vec{x} \wedge E$ (is a Killing vector field in \mathbb{R}^3).
- $v(x) = \bar{g}(V, N)$.
- $\Delta_{\Sigma} v + (\bar{\text{Ric}}(N) + |A|^2) v = 0$, [v is a Jacob function (Fornari, Ripoll - 2004)].
- $\gamma(t) \subset v^{-1}(0)$ is critical point of v .

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- \mathcal{C} contains more than a single point. Let $\gamma : [0, 1] \rightarrow \mathcal{C}$ be a minimizing geodesic joining two points ($\gamma(0), \gamma(1) \in \mathcal{C}$).
- γ is a geodesic in \mathbb{S}_{λ}^2 , $\lambda < r$.
- $\gamma(t)$ is an arc of a great circle.
- Let $\pi \subset \mathbb{R}^3$ be the plane passing through the origin such that $\gamma \subset \pi$, and let E be a unit normal vector in \mathbb{R}^3 orthogonal to π .
- $V = \vec{x} \wedge E$ (is a Killing vector field in \mathbb{R}^3).
- $v(x) = \bar{g}(V, N)$.
- $\Delta_{\Sigma} v + (\bar{\text{Ric}}(N) + |A|^2) v = 0$, [v is a Jacob function (Fornari, Ripoll - 2004)].
- $\gamma(t) \subset v^{-1}(0)$ is critical point of v .
- $v \equiv 0$ (Cheng).

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- \mathcal{C} contains more than a single point. Let $\gamma : [0, 1] \rightarrow \mathcal{C}$ be a minimizing geodesic joining two points ($\gamma(0), \gamma(1) \in \mathcal{C}$).
- γ is a geodesic in \mathbb{S}_{λ}^2 , $\lambda < r$.
- $\gamma(t)$ is an arc of a great circle.
- Let $\pi \subset \mathbb{R}^3$ be the plane passing through the origin such that $\gamma \subset \pi$, and let E be a unit normal vector in \mathbb{R}^3 orthogonal to π .
- $V = \vec{x} \wedge E$ (is a Killing vector field in \mathbb{R}^3).
- $v(x) = \bar{g}(V, N)$.
- $\Delta_{\Sigma} v + (\bar{\text{Ric}}(N) + |A|^2) v = 0$, [v is a Jacob function (Fornari, Ripoll - 2004)].
- $\gamma(t) \subset v^{-1}(0)$ is critical point of v .
- $v \equiv 0$ (Cheng).
- V is tangent to Σ .

- If

$$\mathcal{C} = \{p \in \Sigma; \Psi(p) = \min_{\Sigma} \Psi(x)\},$$

contains a single point. Then, Σ is a topological disk.

- \mathcal{C} contains more than a single point. Let $\gamma : [0, 1] \rightarrow \mathcal{C}$ be a minimizing geodesic joining two points ($\gamma(0), \gamma(1) \in \mathcal{C}$).
- γ is a geodesic in \mathbb{S}_{λ}^2 , $\lambda < r$.
- $\gamma(t)$ is an arc of a great circle.
- Let $\pi \subset \mathbb{R}^3$ be the plane passing through the origin such that $\gamma \subset \pi$, and let E be a unit normal vector in \mathbb{R}^3 orthogonal to π .
- $V = \vec{x} \wedge E$ (is a Killing vector field in \mathbb{R}^3).
- $v(x) = \bar{g}(V, N)$.
- $\Delta_{\Sigma} v + (\bar{\text{Ric}}(N) + |A|^2) v = 0$, [v is a Jacob function (Fornari, Ripoll - 2004)].
- $\gamma(t) \subset v^{-1}(0)$ is critical point of v .
- $v \equiv 0$ (Cheng).
- V is tangent to Σ .
- Since the vector field V on \mathbb{R}^3 is induced by rotations around the axis that is orthogonal to the plane π , and passes through the center of the great circle which contains γ , we see that Σ is rotationally symmetric.

Corollary

Let Σ be a compact free boundary minimal surface in $(\mathbb{B}_r^3, \bar{g})$. Suppose that for all points $x \in \Sigma$,

$$\frac{|A|^2}{\sigma^2} \bar{g}(\vec{x}, N)^2 \leq 2.$$

Then, one of the following situations occurs,

- ❶ either Σ is diffeomorphic to a disk,
- ❷ or Σ is rotationally symmetric with nontrivial topology.

Corollary

Let Σ be a compact free boundary CMC surface in $(\mathbb{B}_r^3, \bar{g})$. If

$$\frac{|\mathring{A}|^2}{\sigma^2} \bar{g}(\vec{x}, N)^2 < \frac{1}{2} \left(2 + \frac{H}{\sigma} \bar{g}(\vec{x}, N) \right)^2,$$

then Σ is diffeomorphic to a disk \mathbb{D}^2 .

Theorem (A., Barbosa, Pereira)

There is $r > 0$ and a minimal surface $\Sigma \subset (\mathbb{B}_r^3, e^{-\frac{|\vec{x}|^2}{4}} \langle, \rangle)$ with strictly convex boundary $\partial\Sigma \subset \partial\mathbb{B}_r^3$ where the condition

$$\frac{1}{\sigma^2} |A|^2 \bar{g}(\vec{x}, \bar{N})^2 \leq 2$$

is satisfied for all point p in Σ .

Remark:

- *Li and Xiong (2017) proved the analogous results for FBMS in a geodesic ball of \mathbb{S}_+^3 and \mathbb{H}^3 .*

Remark:

- *Li and Xiong (2017) proved the analogous results for FBMS in a geodesic ball of \mathbb{S}_+^3 and \mathbb{H}^3 .*
- *Barbosa and Viana (2018) extended Ambrozio-Nunes results for hypersurfaces.*

Remark:

- *Li and Xiong (2017) proved the analogous results for FBMS in a geodesic ball of \mathbb{S}_+^3 and \mathbb{H}^3 .*
- *Barbosa and Viana (2018) extended Ambrozio-Nunes results for hypersurfaces.*
- *Cavalcante, Mendes and Vitório (2018) $\Sigma^2 \subset \mathbb{B}^{2+k}, k \geq 1$.*

We recall that the traceless second fundamental form is defined as

$$\Phi(u, v) = A(u, v) - \langle u, v \rangle \vec{H} \Rightarrow |\Phi|^2 = |A|^2 - n|\vec{H}|^2.$$

We recall that the traceless second fundamental form is defined as

$$\Phi(u, v) = A(u, v) - \langle u, v \rangle \vec{H} \Rightarrow |\Phi|^2 = |A|^2 - n|\vec{H}|^2.$$

Theorem (Cavalcante, Mendes, Vítório - 2018)

Let Σ^2 be a free boundary compact orientable surface immersed in \mathbb{B}^{2+k} , for any positive integer k . If $|\Phi|^2 \leq 2$, then Σ^2 is topologically a disk.

Proof.

Use the blackboard. □

Corollary (Cavalcante, Mendes, Vítório - 2018)

Let Σ^2 be a free boundary compact orientable surface *minimally* immersed in \mathbb{B}^{2+k} , for any positive integer k . If $|A|^2 \leq 4$, then Σ^2 is the flat equatorial disk.

Proof.

Use the blackboard. □

Remark:

- *Li and Xiong (2017) proved the analogous results for FBMS in a geodesic ball of \mathbb{S}_+^3 and \mathbb{H}^3 .*
- *Barbosa and Viana (2018) extended Ambrozio-Nunes results to higher dimension.*
- *Cavalcante, Mendes and Vitório (2018) $\Sigma^2 \subset \mathbb{B}^{2+k}, k \geq 1$.*
- *Barbosa, Freitas, Melo e Vitório (2022) proved a gap theorem for minimal free boundary $\Sigma^n \subset \mathbb{B}^{n+1}$.*

Remark:

- *Li and Xiong (2017) proved the analogous results for FBMS in a geodesic ball of \mathbb{S}_+^3 and \mathbb{H}^3 .*
- *Barbosa and Viana (2018) extended Ambrozio-Nunes results to higher dimension.*
- *Cavalcante, Mendes and Vitório (2018) $\Sigma^2 \subset \mathbb{B}^{2+k}$, $k \geq 1$.*
- *Barbosa, Freitas, Melo e Vitório (2022) proved a gap theorem for minimal free boundary $\Sigma^n \subset \mathbb{B}^{n+1}$.*
- *This same gap condition was used by Meeks, Pérez and Ros (2008) to characterize the plane and the catenoid in \mathbb{R}^3 among properly embedded minimal surfaces without boundary.*

① Lecture 1

- (Brief) Motivation to study Differential Geometry. (done)

② Lecture 2

- Free boundary minimal or CMC surfaces. Gap results. (done)

③ Lecture 3

- Free boundary CMC (hyper)surface in the ball. Stability.

④ Lecture 4

- Some characterization of the critical catenoid.

References:



AMBROZIO, LUCAS; NUNES, IVALDO, *A gap theorem for free boundary minimal surfaces in the three-ball*. arXiv preprint arXiv:1608.05689 (2016).



ANDRADE, MARIA; BARBOSA, EZEQUIEL; PEREIRA, EDNO, *Gap Results for Free Boundary CMC Surfaces in Radially Symmetric Conformally Euclidean Three-Balls*, The Journal of Geometric Analysis, v. 31, p. 8013-8035, 2021.



ROS, ANTONIO; VERGASTA, ENALDO, *Stability for hypersurfaces of constant mean curvature with free boundary*, Geometriae Dedicata, 56, (1995), 19–33.



BARBOSA, EZEQUIEL; CAVALCANTE, MARCOS P.; PEREIRA, EDNO, *Gap results for free boundary CMC surfaces in the Euclidean three-ball* arXiv preprint arXiv:1908.09952 (2019).



NUNES, IVALDO, *On stable constant mean curvature surfaces with free boundary* Mathematische Zeitschrift 287.1 (2017): 473-479.



Many others ...

Thank you for your attention!
See you tomorrow!